

**ODEs - 104285. Semester: Spring. Year: 2012**

**HW-7. You should do it by Sunday June 24 evening**

1. Find a partial solution of the equation

$$P\left(\frac{d}{dt}\right)(y(t)) = e^t \sin t + e^{2t} \cos(3t) + \cos(3t) + e^{4t},$$

where

$$P(\lambda) = (\lambda^2 - 2\lambda + 2)^7 (\lambda^2 - 4\lambda + 13)^9$$

(requires 8-10 min)

2. Let

$$x' = Ax, \quad A = \begin{pmatrix} 3 & 1 & 4 & 0 \\ -2 & 3 & 2 & 1 \\ 7 & 4 & 0 & 3 \\ 0 & 0 & 1 & 2 \end{pmatrix}, \quad x = \begin{pmatrix} x_1(t) \\ x_2(t) \\ x_3(t) \\ x_4(t) \end{pmatrix}, \quad x(0) = \begin{pmatrix} 1 \\ 1 \\ 1 \\ 0 \end{pmatrix}.$$

Find  $a, b, c \in \mathbb{R}$  such that  $x_2(t) = a + bt + ct^2 + o(t^2)$  as  $t \rightarrow 0$ .

(requires 5-7 min)

3. Find the set of all solutions of the system  $x'_1 = x_1 + x_2$ ,  $x'_2 = 6x_1 - 4x_2$  (without exponent of a matrix)

(requires 5-8 min)

4. Find  $e^A$  where  $A = \begin{pmatrix} 1 & 1 \\ 6 & -4 \end{pmatrix}$  (without series in the answer).

Hint: find solution  $x(t)$  of the system in problem 3 satisfying the initial condition  $x(0) = \begin{pmatrix} 1 \\ 0 \end{pmatrix}$ . you know that  $x(t) = e^{tA} \begin{pmatrix} 1 \\ 0 \end{pmatrix}$  and consequently  $e^A \begin{pmatrix} 1 \\ 0 \end{pmatrix} = x(1)$  which allows you to find the first column of  $e^A$ . In a similar way you can find the second column.

Requires 10 min.

4. Let

$$T = \begin{pmatrix} 1 & 3 & -2 \\ 2 & 7 & 0 \\ 1 & 1 & 3 \end{pmatrix}, \quad J = \begin{pmatrix} 3 & 0 & 0 \\ 0 & 3 & 0 \\ 0 & 0 & -2 \end{pmatrix}.$$

Find the set of all solutions of the system  $x' = Ax$  where  $A = TJT^{-1}$

(requires 1 min since you know a basis of  $\mathbb{R}^3$  consisting of eigenvalues of  $A$ ).

5. Let  $A$  be a real  $2 \times 2$  matrix with eigenvalue  $2 - 3i$  and corresponding eigenvector  $\begin{pmatrix} 5 + 4i \\ 3 - 2i \end{pmatrix}$ . Find the set of all real solutions of the system  $x' = Ax$ . No complex numbers, signs Re, Im in the final answer.

Hint. Find a basis of complex-valued solutions consisting of vector functions  $x^*(t)$  and conjugate (tsamud)  $\bar{x}^*(t)$ , then (as we did many times) the real and the imaginary part of  $x^*(t)$  is a basis of the vector space of real solutions.

(requires 8-9 min)